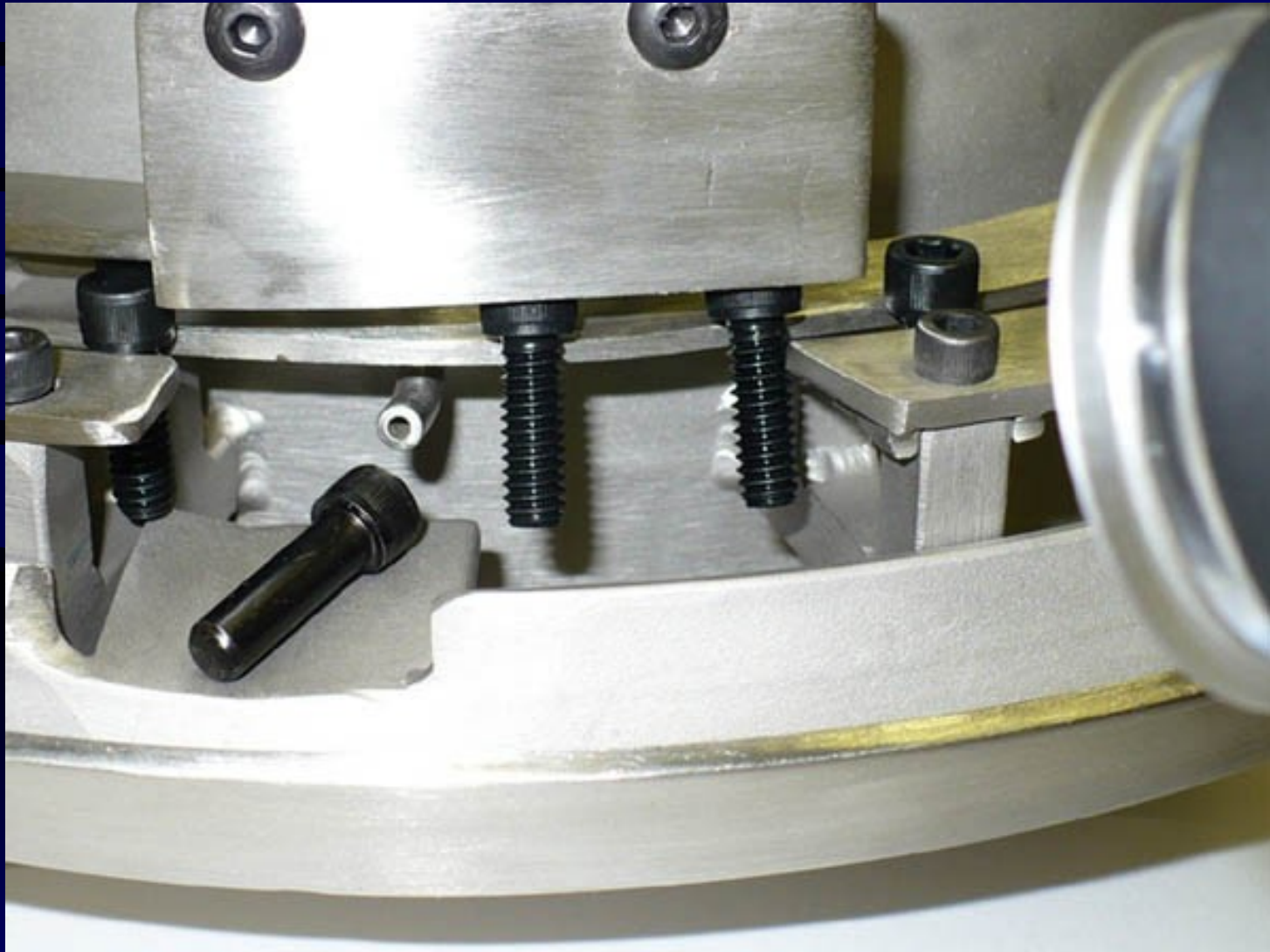


Vision is used to detect an indent feature to determine proper side for side orientation



A Camera is in place to reject parts with missing features out of the feeder as a sorting option



Vision used to select off mis-oriented parts

